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Research in robust control theory has been one of the most active areas of mainstream systems theory since the late 70s. This research activity has been at the confluence of dynamical systems theory, functional analysis, matrix analysis, numerical methods, complexity theory, and engineering applications. The discipline has involved interactions between diverse research groups including pure mathematicians, applied mathematicians, computer scientists and engineers.

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The resulting Q-parameterization is ubiquitously used in control theory, eg, in robust control, 15, 16 computer-aided design, 17 gain scheduling, 18,19 model predictive, 20 hybrid, 21 and adaptive ...

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